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An Almost Integration-free Approach to Ordered Response Models

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An Almost Integration-free Approach to Ordered Response Models

Abstract

In this paper we propose an alternative approach to the estimation of ordered response models. We show that the Probit-method may be replaced by a simple OLS-approach, called P(robit)OLS, without any loss of efficiency. This method can be generalized to the analysis of panel data. For large-scale examples with random fixed effects we found that computing time was reduced from 90 minutes to less than one minute. Conceptually, the method removes the gap between traditional multivariate models and discrete variable models

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1. Introduction.

The main task of econometric methodology is to estimate relationships between variables y and variables x. The oldest example is OLS, where we try to explain a variable y by a linear combination of variables x. The expected *structural* relation is then $y \approx \beta' x + \beta_0$, which we make exact by adding an error term, viz., $y = \beta' x + \beta_0 + \varepsilon$. It is assumed that the random vector of explanatory variables and the random residual are mutually independent¹. The unknown β 's are estimated by minimizing the sum of squared residuals. Mostly this procedure is defended on the basis of probabilistic assumptions under which the OLS- procedure is identical with maximum-likelihood estimation. There is now a well-established family of methods, like simultaneous equations, principal components, etc., in short the body of literature, which is called the 'linear model' or 'multivariate statistics', that may be seen as generalizations of the OLS- model.

There are however situations where we have difficulty with applying such models. It may be that the variable to be explained is ordinally continuous. We think of preference orderings where situations, conditions or commodity bundles x are ordered according to a preference ordering \prec . Under rather general conditions such a preference ordering may be described by a utility function U(x), such that $x^{(1)} \prec x^{(2)}$ if and only if $U(x^{(1)}) < U(x^{(2)})$. We know, following Pareto (1906) and Debreu (1959), that in such a case only the indifference curves, described by equations 'U(x) = constant', are determined and observable, but that the function U(.) as such has no cardinal interpretation. It is just a labeling system, that may be replaced by any function

¹ In the literature one chooses often the slightly more general assumption that the explanatory variables and the residual are uncorrelated. We prefer the independence assumption as being more intuitive.

 $\tilde{U}(.) = \varphi(U(.))$, where $\varphi(.)$ is a monotonically increasing function on the range of U(.). The situation may be even more complicated if the preference ordering is only discretely observed, e.g., in terms of verbal categories like 'bad', 'sufficient', 'good' or numerical categories 1,2,...7, where no cardinal meaning can be assigned to the numerical values. Then we have *ordered response sets* $A_1 \prec A_2 \prec ...$. Such problems are mostly approached by using an Ordered Probit (OP) or an Ordered Logit -model.

The Ordered Probit (OP) and Ordered Logit (OL) models belong to the main traditional statistical workhorses in applied econometric studies. They are applied to cases where the range of possible events can be ordered or ranked in terms of more or less preferred, higher or lower, better or worse, more or less probable, more or less propensity to be employed. These are ordered response models. The model is implemented by the introduction of a *latent variable* $Y = f(X, \varepsilon; \beta) = X'\beta + \varepsilon$, where the function f(.) is mostly taken to be linear after suitable transformation of the variables involved. Then we postulate that the chance on the observation of A_i is $P(A_i) = P(Y \in A_i)$, where we assume that the intervals $A_i = (\mu_{i-1}, \mu_i]$ constitute a partition of disjoint intervals on the real axis. Maximization of the log-likelihood with respect to the 'nuisance parameters' μ_i and the parameters β yields the estimates. This is the usual approach when we deal with 'satisfactions' or 'propensities'. Those 'satisfactions' or 'propensities' may deal with how satisfied individuals are with their life, with their income, or with a specific opera performance in terms of verbal descriptions, ranging from 'terrible' to 'delighted'. The same holds for individuals that we may order in, e.g., being less or more likely to be employed. Such variables are frequently encountered in economics and especially in the now flourishing subjective satisfaction literature². Beyond economics ordered- response models are used in many other fields like psychology, sociology, political science, medicine and biology. We refer for still relevant surveys to Amemiya (1981) and Maddala (1983). More recent surveys are by Dhrymes (1986), Long (1997), DeMaris (2004), and Greene (2005). The ordered response models entail computational problems. However, in modern software packages (e.g. STATA, LIMDEP) the problems involved in the estimation of a single equation (Probit, Logit) have been sufficiently tackled. Nevertheless, when we try to apply ordered response models on more general models than the simple OLS-equation we easily run into difficulties. For instance, when we like to apply the method in panel analysis where we want to take into account the panel structure either by assuming that the error terms between different observations of the same individual are correlated (individual random effects) or by introducing individual fixed effects (see Greene, 2005), many computational problems appear, when the onedimensional integrals have to be replaced by multi-dimensional integrals, where integration problems tend to become overwhelming. Another example is the estimation of a system of equations. Although the conceptual model is just the traditional linear model, there arise problems when we like to extend the usual econometric toolkit, if latent variables are involved. Our method is much easier to implement, as it does not require many integrations. To be more precise, if the number of distinct response categories is k, we need (k-1) normal integrations, in most practical cases a number smaller than 10. In the traditional OP- approach we need N integrals, one per observation n. If we take into

² See, e.g., Clark and Oswald, 1994; DiTella et al., 2001; Easterlin, 2001; Ferrer-i-Carbonell, 2005; Ferreri-Carbonell and Frijters, 2004; Frey and Stutzer, 2002; Blanchflower and Oswald, 2004; Frijters, Haisken-DeNew, and Shields, 2004; van Praag, 1971;Van Praag and Ferrer-i-Carbonell, 2004; and Van Praag, Frijters, and Ferrer-i-Carbonell, 2003.

account that Probit-estimation is typically solved by means of a few iteration rounds, say 5, then the number of integrations is 5N. So, if we have 10 response categories and 2000 observations, the traditional approach requires 10,000 integral computations, why for our method 9 integrals are sufficient. In our empirical results in Section 6 we will see that this will give a tremendous reduction of computer time. In a rather realistic model of a random fixed effect panel model the traditional approach requires about one and a half hour, while the same estimation by our method requires about a minute.

When we consider the situation we feel that the ordered response literature is much more built up from solutions to isolated problems than the general linear model literature and that therefore it stands somewhat apart as a different field from mainstream statistics and econometrics.

In this paper we will try to bridge that gap by proposing a specific OLS –approach that avoids the integration problems. In section 2 we shall have a close look at OP and its relationship with OLS. In section 3 we introduce an alternative to Probit, which we will call the Probit OLS (POLS)- method. In Section 4 we compare the POLS –approach with Ordered Probit. Our conclusion is that they are equivalent. In Section 5 we compare the POLS –approach with Ordered Probit on the basis of an empirical data set. The empirical findings confirm the equivalence of both methods. In Section 6 we apply the method to a panel data set with individual random effects. In Section 7 we compare the POLS-method with the Linear Probability method in the specific case of a binary response variable. It is easily seen that much of what we do lends itself for a Logit-type treatment as well; we consider and evaluate this briefly in Section 8. In Section 9 we draw some conclusions.

The main conclusion of this paper is that it seems possible to enroll all ordered response problems within the body of the well-established statistical –econometric toolkit of linear models. Computationally, it implies a significant reduction of computing time. Therefore, there would be hardly any need for a separate body of computationally hard methods dealing with ordered response analysis. For other empirical applications in a panel context or/and where the latent variables appear 'at the left-hand side' as well, we refer to Van Praag and Ferrer-i-Carbonell (2004), Van Praag, Frijters, and Ferrer-i-Carbonell (2003), and Van Praag and Baarsma (2005).

2. The relation between OLS and the Ordered Probit (OP) model.

In this section we will look for the relation between the OLS –estimators and the corresponding Probit-estimator, if the dependent variable is observed through an ordered response mechanism. In order to avoid unnecessary abstraction we cast our analysis in terms of a satisfaction context. It will be obvious that the analysis as such is completely general.

We consider individual self-reported financial satisfaction³ μ , which is assumed to depend on log-income (*inc*) and log-family size (*fs*) according to the relation

$$\beta_1.inc + \beta_2.fs + \beta_0 + \varepsilon = \mu \tag{2.1}$$

or

$$X'\beta + \varepsilon = \mu \tag{2.2}$$

³ For the context see also Van Praag and Ferrer-i-Carbonell, 2004, chapter 2

for short. For each value of μ this equation describes an 'equal satisfaction' - or indifference –line on the (*inc*,*fs*, ε) -space. We assume X and ε to be random and mutually independent. It follows that μ is a random variable as well. Moreover, we assume ε to be N (0,1)-distributed.

The *trade-off* ratio between *inc* and *fs* is defined by β_2 / β_1 . If personal conditions change by Δinc and Δfs such that $\Delta inc = (-\beta_2 / \beta_1) \cdot \Delta fs$, the individual stays on the same indifference curve.

Let us now assume, quite realistically, that it is impossible to distinguish between very small satisfaction differences.

This implies that the dense net of indifference curves is replaced by a set of just *k* nonoverlapping 'indifference strips' on the (*inc*, *fs*)-space (see Figure 1). Each indifference strip *i* has a lower and upper boundary, corresponding to the indifference curves labeled by μ_{i-1} , and μ_i . The curve corresponding to the level $\overline{\mu}_i$ is a 'group-average' curve in a sense to be made precise later on.

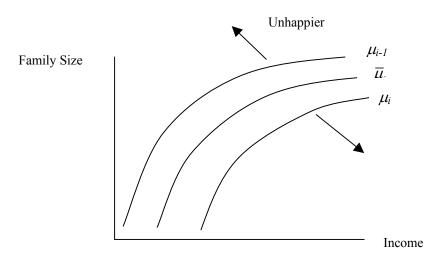


Fig. 1. Indifference curves in the (income, family size) – space.

Since ε is assumed to be N(0,1)- distributed, the likelihood of observation n, being in response category i_n is

$$P(\mu_{i-1} < x'_n \beta + \varepsilon \le \mu_i) = P(\mu_{i-1} - x'_n \beta < +\varepsilon \le \mu_i - x'_n \beta)$$

$$N(\mu_i - x'_n \beta) - N(\mu_{i-1} - x'_n \beta)$$
(2.3)

where N(.) stands for the standard-normal distribution function.

Applying the ML-estimation principle we differentiate the logarithm of (2.2) with respect to β yielding

$$\frac{\partial \ln(P)}{\partial \beta} = \frac{n(\mu_i - x'_n \beta) - n(\mu_{i-1} - x'_n \beta)}{N(\mu_i - x'_n \beta) - N(\mu_{i-1} - x'_n \beta)} \cdot (-x_n)$$
(2.4)

Now we have (see, e.g., Johnson and Kotz, p.81, 1970 and Maddala, p.366, 1983) for the conditional expectation of the normal distribution the general formula

$$E(X;m,s|A < X \le B) = m + \frac{n(\frac{A-m}{s}) - n(\frac{B-m}{s})}{N(\frac{B-m}{s}) - N(\frac{A-m}{s})}.$$
(2.5)

where X is N(m,s)-distributed.

Using this formula we may rewrite (2.4) as

$$\frac{\partial \ln(P_n)}{\partial \beta_j} = E(\varepsilon; 0, 1 | \mu_{i-1} - x'_n \beta < \varepsilon \le \mu_i - x'_n \beta).(-x_{n,j})$$
(2.6)

or

$$\frac{\partial \ln(P)}{\partial \beta_{j}} = E(\varepsilon; 0, 1 | \mu_{i-1} < \mu \le \mu_{i}).(-x_{n,j})$$

$$= [E(\mu - x'_{n}\beta; 0, 1 | \mu_{i-1} < \mu \le \mu_{i})].(-x_{n,j})$$
(2.7)

If we sum over the observations we get the normal equation system

$$\sum_{n=1}^{N} \frac{\partial \ln(P_n)}{\partial \beta_j} = \sum_{n=1}^{N} \left[E(\mu; 0, 1 | \mu_{i_n - 1} < \mu \le \mu_{i_n}) - x'_n \beta \right] \cdot (-x_{n,j}) = 0$$
(2.8)

We see that this is just the familiar orthogonality condition of regression analysis, where the variable μ is replaced by its conditional expectation $E(\mu; 0, 1 | \mu_{i_n-1} < \mu \le \mu_{i_n}) \stackrel{def}{=} \overline{\mu}_i$, yielding the system

$$(X'X)\beta = X'\overline{\mu} \tag{2.9}$$

This is equivalent to regressing $\overline{\mu}$ on X instead of μ itself. The difference $(\mu - \overline{\mu}_i)^{def} = \varepsilon_{i,within}$ may be seen as a measurement error with respect to the variable μ to be explained. Its expectation is zero and its total variance is σ^2_{within} . The regression equation becomes

$$\overline{\mu} = X'\beta + \varepsilon - \varepsilon_{within} \tag{2.10}$$

yielding a consistent estimator of β . However, compared to the case of continuous observation where μ itself would be observable this estimator has a greater standard deviation caused by the increased residual variation.

Consider now the background - model

$$\mu_n = X'_n \beta + \varepsilon_n \tag{2.11}$$

where β is assumed to be known. It implies a labeling system for the indifference curves. When $\varepsilon = \varepsilon_n$ the observation *n* lies on the indifference curve $\mu_n = X'_n \beta + \varepsilon_n$.

If X is a random vector with expectation \overline{X} and variance –covariance matrix Σ_{XX} , it follows that we know the distribution of the indifference curve labels μ , *if* we know the distribution of X and ε . We have $E(\mu) = \beta' \overline{X}$ and $\operatorname{var}(\mu) = \beta \Sigma_{XX} \beta + 1$. In view of the fact that the distance between indifference curves is defined by using the likelihood $\int_{\mu_{t-1}}^{\mu_{t}} e^{-\frac{1}{2}(\mu - \beta' x_{n})^{2}} d\mu$, where the distance $(\mu - \beta' x_{n})^{2}$ appears in the exponent, the resulting labeling system may in fact be interpreted as a cardinalization.

If we stick to the ordinal approach to utility and satisfaction, our only information refers to the shape of the indifference curves. The information on β , or rather on the slope described by the trade-off ratios, is the same, irrespective of the specific labeling system used. We will come back to this later.

3. The Probit OLS (POLS) - approach.

The regression approach to Probit, as outlined in equations (2.8)-(2.10), is unfeasible in practice as we do not know the distribution of μ . Consequently, the conditional expectation in (2.7) cannot be computed. In the POLS- approach we start from the other end so to speak. We assume that the labels μ of the indifference curves within a population are distributed according to a continuous distribution function $G(\mu)$, that is, there is no indifference curve with a discrete mass of observations on it. Then $G(\mu)$ is the fraction of the population that is situated on or at a lower satisfaction level than the one associated with the indifference curve μ . We repeat that in the ordinal approach there is no cardinal meaning attached to the values μ . This means that we can replace the values μ by $\tilde{\mu} = \varphi(\mu; \zeta)$, where the function φ is monotonically increasing to preserve the order and where ζ is a set of φ -specific parameters. Notice that if $\mu = \mu(x; \beta)$, then $\tilde{\mu} = \varphi(\mu(x;\beta);\zeta)$. This implies that both representations describe the same net of indifference curves. The distribution function of the distribution of $\tilde{\mu}$ is $H(\tilde{\mu}) = G(\varphi^{-1}(\tilde{\mu}))$. This shows that the distribution function of the label distribution depends on the specific labeling system. Inversely, it follows that the label distribution may be *any* continuous distribution on the real axis, depending on the appropriate choice of the re-labeling function $\varphi(.)$.

It follows that there is a specific labeling system, for which the distribution of $\tilde{\mu}$ will be standard normal, i.e., $H(\tilde{\mu}) = N(\tilde{\mu}; 0, 1)$. We call this labeling system the *normal* labeling system. We drop the *tilde* from now on.

Let us now assume that we observe satisfaction in terms of a few discrete response categories, for example ranging from 'very dissatisfied' to 'very satisfied'.

The range of labels is partitioned in response categories that represent k adjacent intervals $(\mu_{i-1}, \mu_i]$, such that a response I=i (i=1,...,k) implies that the latent variable $\mu \in (\mu_{i-1}, \mu_i]$. We define $\mu_0 = -\infty, \mu_k = \infty$. The categorical frequencies (i.e. the frequency of responses found in each k category) are $p_1, ..., p_k$. Now, if we start off from the normal labeling system the variable μ is N(0,1)-distributed in the population. Moreover, we assume a model where μ may be decomposed into a structural part, say f(X) and a residual part ε , such that the two components are mutually independent. A rather deep theorem in probability theory, first proved by H. Cramèr in 1937 (see Feller, 1966, Ch. XV, 8, also Rao, 1973, p.525), states that if μ is normally distributed and if it is the sum of two mutually independent random variables, say f(X) and a residual part ε , then those two variables have to be normally distributed as well. It implies that the structural part f(X) will be normally distributed as well. This does not imply that all Xvariables separately have to be normal, for they are not assumed to be mutually independent. But it does imply that f(X) cannot be restricted to a proper subset of the real axis $(-\infty, \infty)$ only.

Given the distribution of μ over the population we may estimate the μ_i 's in a simple manner by solving the equations

$$p_i = N(\mu_i) - N(\mu_{i-1}) \quad (i = 1, ..., k-1)$$
(3.1)

(see for similar thoughts also Terza (1987), Stewart (1983), and Ronning and Kukuk (1996)).

These are (*k*-1) equations in (*k*-1) unknowns $\mu_1, ..., \mu_{k-1}$. Although we do not know the exact value of individual μ 's, we now know at least that it lies within a specific interval. Notice that this result does not depend on the *x*-values, not brought into play yet, but only on the distribution of the response categories, that is, the unconditional distribution of μ . Let us now assume that we try to explain the variable μ by a linear model

$$\mu_n = \sum_{j=0}^m \beta_{POLS,j} X_{jn} + \varepsilon_n \tag{3.2}$$

where $X_{0n} \equiv 1$ and β_0 the intercept⁴.

Although μ_n cannot be directly observed, we may calculate its conditional expectation (see (2.5)) $\overline{\mu}_{i_n} = E(\mu | \mu_{i-1} < \mu \le \mu_i)$. As already said, for the normal distribution holds the formula (see, e.g., Maddala, 1983, p.366)

$$\overline{\mu}_{i_n} = E(\mu \mid \mu_{i_n-1} < \mu \le \mu_{i_n}) = \frac{n(\mu_{i_n-1}) - n(\mu_{i_n})}{N(\mu_{i_n}) - N(\mu_{i_n-1})}$$
(3.3)

The variable $\overline{\mu}_{i_n}$ is a discrete random variable with chances $p_i = N(\mu_i) - N(\mu_{i-1})$. Now we take $\overline{\mu}_{i_n}$ as a proxy for μ_n . We write $\mu_n = \overline{\mu}_{i_n} - E(\varepsilon \mid \mu_{i_n-1} < \mu \le \mu_{i_n})$ and we regress $\overline{\mu}_{i_n}$ on the variables *x*. We estimate the model

 $^{^{4}}$ We denote random variables by capitals and their values by lower case.

$$\overline{\mu}_{i_n} = \sum_{0}^{m} \beta_{j,POLS} X_{j,n} + \varepsilon_n - E(\varepsilon \mid \mu_{i_n-1} < \mu \le \mu_{i_n})$$
(3.4)

Notice that (2.10) and (3.4) are identical except for a factor of proportionality.

We have the following variance decomposition. The total variance of the continuous μ is $\sigma^2(\mu) = 1$ by definition. The variable $\overline{\mu}_{i_n}$ we observe is a class mean. Its variance is $\sigma^2(\overline{\mu}_{i_n}) < 1$. The difference $1 - \sigma^2(\overline{\mu}_{i_n})$ is the *information loss* by observing the discretized variable $\overline{\mu}_{i_n}$ instead of the continuous latent variable μ behind it. Hence, we get the decomposition.

$$(1 - \sigma^2(\overline{\mu}_{i_n})) + \operatorname{var}(\sum_{0}^{m} \beta_i X_{i_n}) + \sigma^2(\varepsilon_n) = 1$$
(3.5)

The observed \dot{R}^2 is

$$\dot{R}^{2} = \frac{\operatorname{var}(\sum_{0}^{m} \beta_{i} X_{in})}{\operatorname{var}(\sum_{0}^{m} \beta_{i} X_{in}) + \sigma^{2}(\varepsilon_{n})}$$
(3.6)

This is an overestimate of the *true* R^2 , which equals

$$R^{2} = \frac{\operatorname{var}(\sum_{0}^{m} \beta_{i} X_{in})}{(1 - \sigma^{2}(\overline{\mu}_{i_{n}})) + \operatorname{var}(\sum_{0}^{m} \beta_{i} X_{in}) + \sigma^{2}(\varepsilon_{n})} = \operatorname{var}(\beta' X)$$
(3.7)

Or in words, the larger the information loss due to discretization, the larger apparently the variance explained. It also implies that the residual variance is under-estimated, and hence that the standard deviations of the estimators are underestimated as well. Therefore, the corresponding *t*-ratios are overestimated. The correction factor Δ is easily assessed to be

m

$$\Delta = \frac{1 - \operatorname{var}(\sum_{i=0}^{m} \beta_i x_{in})}{\sigma^2(\varepsilon_n)}$$
(3.8)

It stands to reason that the POLS-method can be used for non-linear models as well after suitable transformation.

4. Comparison between POLS and Ordered Probit.

The question is now how traditional Ordered Probit compares with the POLS-approach. The traditional model in OP is again

$$Y_n = \sum_{i=0}^m X'_{in} \beta_{i,OP} + \varepsilon_n \tag{4.1}$$

However, the assumptions of the OP- model differ from those of the POLS- model. In OP the error term is normal N(0,1), but the structural part $\sum_{0}^{m} \beta_{i,OP} X_{in} = (X'_{n} \beta_{OP})$ is not

necessarily normal. That implies that the population distribution of the latent variable Y is not necessarily normal either. However, in practice there are two reasons why there is at least a reasonable chance that Y will be approximately normal as well. First, the distribution of many explanatory variables is frequently nearly normal in the population under study. Second, in econometric practice variables are frequently transformed prior to the analysis in such a way that their distribution in the population (unintendedly) becomes approximately normal. An interesting example is income. Frequently we take log-income as explanatory variable, which is approximately normally distributed in populations. It is also possible to transform explanatory variables X on purpose by a oneone monotonous transformation such that the sample distributions of the transform, say $\tilde{X} = \varphi(X)$, are N(0,1)-distributed. Thus, the sum $\sum \beta_j \tilde{X}_{j,n}$ is ensured to be normal. Finally, the Central Limit Theorem is at work. Mostly the number of explanatory variables is between five and ten, which is too small a number to warrant the claim of accurate normality of their sum, but in practice the difference is mostly negligible. If that is true, we see that (2.10) and (3.4) are identical systems except for a factor of proportionality. And inversely, if we find that the systems are different in more than a factor of proportionality we may infer that the structural part is not approximately normally distributed in the population.

Under the Probit assumptions the variance of the unknown error is set equal to one, $\sigma^2(\varepsilon) = 1$. It follows that the variance of the latent Y_{OP} equals

$$\sigma^2(\mu_{OP}) = \sigma^2(\varepsilon) + \sigma^2(X'_n\beta_{OP}) = 1 + \sigma^2(X'_n\beta_{OP})$$
. Hence, the variance of the Probit latent variable is larger than that of the μ_{POLS} in the POLS-approach. If both models describe the same indifference curves, it follows that the coefficients β_{OP} and β_{POLS} must have a

fixed ratio
$$H = \frac{\beta_{OP}}{\beta_{POLS}} = \frac{\sqrt{1 + \sigma^2(X'_n \beta_{OP})}}{\sigma(\overline{\mu})}$$
. Let us now assume that $E(Y_{OP}) = 0$. This

implies the identification of the intercept $\beta_{0,OP} = -E(X'_n\beta_{OP})$.⁵

The chance on a response *i* in the Probit- model is

$$P(\mu_{i-1} < \mu_{OP} \le \mu_{i}) = P(\mu_{i-1} - x'\beta < \varepsilon \le \mu_{i} - x'\beta)$$

$$= N(\mu_{i} - x'\beta) - N(\mu_{i-1} - x'\beta)$$
(4.2)

The unknown 'nuisance parameters' (μ) are found by solving the triangular system

$$\frac{1}{N} \sum_{n \in A_1} \{ N(\mu_1 - x'_n \beta_{OP}) \} = p_1$$

$$\frac{1}{N} \sum_{n \in A_2} \{ N(\mu_2 - x'_n \beta_{OP}) - N(\mu_2 - x'_n \beta_{OP}) \} = p_2$$
(4.3)
.....

where A_i stands for the set of respondents with response *i*. Notice now that if $(X'_n \beta_{OP})$ is (approximately) normal the first sum tends to the marginal distribution function

⁵ We notice that in Ordered-Probit analysis either β_0 or the first nuisance parameter μ_1 is set at zero. This procedure is needed for identification and does not imply a loss of generality. We partition if needed $\beta = (\beta_0, \beta_1)$.

 $N(\mu_1; 0, 1 + \sigma^2(x'_n \beta_{OP}))$. Similarly, the second term tends to $[N(\mu_2; 0, 1 + \sigma^2(X'_n \beta_{OP}) - N(\mu_1; 0, 1 + \sigma^2(X'_n \beta_{OP}))]$ and so on. This is the system (3.1) except for a different variance. It follows that the Probit - μ 's are related to the POLS - μ 's according to the relation $\mu_{OP} = \sqrt{1 + \sigma^2(X'_n \beta_{OP})} \cdot \mu_{POLS}$.

If (2.10) and (3.4) are completely equivalent, except for a factor of proportionality, it follows that POLS and OP are equivalent. The *t*- values of both methods are the same, as the factor $\sqrt{1 + \sigma^2(X'_n\beta_{OP})}$ cancels out. Hence, both methods would be equally efficient. It follows that the observed overestimation in POLS, due to discrete observation, of the *t*-values and of R^2 holds for Probit as well.

5. Empirical illustration.

We applied the above ideas on the Financial Satisfaction Question, which appears in the German Socio-Economic Panel (GSOEP, wave 1996) and in many other surveys as well. This question runs as follows:

How satisfied are you with your household income?

(Please answer by using the following scale, in which 0 means 'totally unhappy' and 10 means 'totally happy')

We explained the answer to this question by two variables, viz. log(household income)(lny) and log (family size) (ln*fs*) according to the equation

$$\overline{\mu}_{i_n} = \beta_{POLS,1} \ln(y_n) + \beta_{POLS,2} \ln(fs_n) + \beta_{POLS,0} + \overline{\varepsilon}_n$$
(5.1)

where $\overline{\varepsilon}_n$ stands for the composite error term in (3.4).

We estimated this equation by POLS and by the traditional OP- method. We present the estimation results of this equation side by side in Table 1.

	Ordered Probit		POLS		
	Coeff.	t-ratio	Coeff.	t-ratio	
Ln(y)	0.487	15.070	0.454	15.230	
Ln(fs)	-0.189	-5.690	-0.176	-5.680	
Constant			-3.596	-15.11	
N = 5179					
Log.Like.	-9650				
Log.Like. R ²			0.0429		
Adjust. R ²			0.0425		
Trade-off-ratio β_2 / β_1	-0.388		-0.387		

Table 1. Estimates of the same relation by OP and POLS⁶. Data:GSOEP, 1996

The intercept terms are now shown in the table.

As predicted in Section 5, we see that both estimates (Probit and POLS) look rather similar. The important point is that the trade-off ratio β_2 / β_1 , that is defining the shape of the indifference curve, is virtually the same for both cases. The t-ratios are the same as well. Hence, we conclude that OP and POLS are here equivalent indeed.

It is frequently thought that the number of response categories k is irrelevant for the estimation. This is however not true. We tried the two regression methods on a transformed data set, where we had just two response categories 'low' and 'high' financial satisfaction. The border was laid at such a point that both response classes contain about half the sample, hence the information loss is maximal. The result is a dependent variable that takes the value 0 if *financial satisfaction* is equal to or smaller

⁶ Similar results are presented in Chapter 2 in Van Praag and Ferrer- i –Carbonell (2004).

than 7 and value 1 otherwise [8 to 10]. There are 2.533 observations with value 0 and 2.646 with value 1.The regression results running a Probit and an OLS on this 0/1 transformed variable are given in Table 2.

Table 2. Probit and POI	LS on a dichot	omous samp	ole grouping	g.
	BiProbit		POLS, 2 values	
	Coeff.	t-ratio	Coeff.	t-ratio
Ln(y)	0.551	13.580	0.339	13.900
Ln(fs)	-0.260	-6.320	-0.161	-6.330
Constant	-4.288	-13.260	-2.657	-13.640
N = 5179				
Log.Like.	-3493			
R^2			0.0362	
Adjust. R ²			0.0358	
Trade-off-ratio β_2 / β_1	-0.47		-0.47	

We see that the trade-off coefficients and the *t*-values are again the same for both approaches. However, somewhat surprisingly, we see that the trade-off coefficient is 0.47, which is significantly different from the value 0.38, found with the finer categorization of Table 1. We shall not go too far in considering this difference here. However, it is a sign that the underlying indifference curves are not parallel to each other, as the trade-off changes when we shift from one satisfaction level to the other. The difference between both estimates is caused by a different grouping.

Finally, we look at the distribution of $(X'_n \beta_{OP})$ over the sample. We present the graph of the distribution in fig. 2, which shows that the distribution looks rather normal indeed. The usual normality tests on skewness, kurtosis and the Jarque-Bera test do not reject the normality assumption.

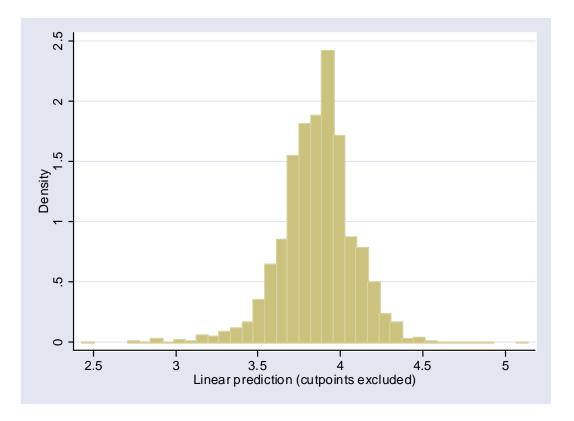


Figure 2. Density of the linear prediction according to Ordered Probit.

6. An application to panel-data.

This method is especially attractive for panel data analysis, where the inclusion of individual effects with ordered response variables is troublesome. Instead if the POLS method is used, panel data analysis becomes as simple as with linear models. Here we present one example. Again, we use the Financial Satisfaction data from the German SOEP- data set covering the period 1992-1996. We assume the model

$$\mu_{nt} = \beta_1 .inc_{nt} + \beta_2 .fs_{nt} + \beta_0 + \varepsilon_n + \eta_{nt}$$

with $E(\varepsilon_n) = E(\eta_{nt}) = 0, \quad E(\varepsilon_n . \eta_{nt}) = 0$
 $\sigma^2(\varepsilon_n) = \sigma_{\varepsilon}^2, \quad \sigma^2(\eta_{nt}) = \sigma_n^2$ (6.1)

The random effect and the white noise are both assumed to be normally distributed. We estimated the model by Ordered Probit using STATA and by our POLS –approach. We find the following results, presented in Table 3.

	OP, rando	OP, random effects		POLS, random effects	
	Coeff.	t-ratio	Coeff.	t-ratio	
Ln(y)	0.439	21.240	0.669	22.260	
Ln(fs)	-0.248	-11.170	-0.357	-11.040	
Constant			1.955	8.210	
Number of observations	25609		25609		
Number of individuals	7807		7807		
Log.Like.	-48172.8				
R ² : Within			0.002		
Between			0.074		
overall			0.038		
Var (ind. random effect)/					
Var (total unexplained)	0.377		0.344		
Trade-off-ratio β_2 / β_1	-0.566		-0.534		

Table 3. Estimates of the same relation by OP and POLS with random effects.Data:GSOEP, 1992-1996

The intercept terms are now shown in the table.

As expected, we find again that the two methods lead to similar results. However, there is a remarkable difference between the running times of the two methods. The traditional method via standard STATA (using the "reoprob" command) takes about 1.5 hour, while the POLS approach, using "xtreg" on the transformed answers, requires less than a minute running time.

For more applications we refer to Van Praag and Ferrer-i-Carbonell (2004), e.g. Chapter 6 with a free error- covariance matrix.

7. The link between BI-POLS and the linear probability model.

There is an interesting link between the BIPOLS-model and the so-called linear probability (LP) -model (see e.g. Heij et al., 2004, p.439). The linear probability model is of an extreme simplicity. The variable *Y* is a binary dependent variable assuming the values 0 and 1. It is assumed that $P(Y = 1) = X'\beta + \beta_0$. It is explained by the regression equation

$$Y = X'\beta + \beta_0 \tag{7.1}$$

The serious literature rejects this model for some reasons, notably because the RHS in (7.1) can assume values outside the interval [0,1]. The model is logically inconsistent. Nevertheless, the estimation method is frequently used in practice, because it is simple and the trade-off ratios are remarkably similar to those found with Probit-analysis. Using our approach we can now understand why this is and must be the case.

Consider the BIPOLS- analogue, where we assign the values $\overline{\mu}_1, \overline{\mu}_2$ to the lower and upper category, respectively. Averaging over the lower and upper category we find

$$\overline{\mu}_{1} = \overline{X}_{1}' \beta_{POLS} + \beta_{0,POLS}$$

$$\overline{\mu}_{2} = \overline{X}_{2}' \beta_{POLS} + \beta_{0,POLS}$$
(7.2)

Now we remind the reader that the choice of the values $\overline{\mu}_1, \overline{\mu}_2$ depends on the specific identification rule, where we assumed that the label- variable μ is N(0,1)-distributed. We

may use other scaling and position parameters, such that $\overline{\mu}_1, \overline{\mu}_2$ become equal to zero and one. We solve the system

$$0 = \gamma(\bar{X}_{1}'\beta_{POLS}) + \delta.\beta_{0,POLS}$$

$$1 = \gamma(\bar{X}_{2}'\beta_{POLS}) + \delta.\beta_{0,POLS}$$
(7.3)

for γ and δ . It follows that if we identify μ by assuming μ to be $N(\gamma, \delta/\gamma)$ -distributed, then BIPOLS is equivalent to the Linear Probability method. As POLS estimates the trade-off ratios as efficiently as Probit, it follows that LP is just as good as Bi-Probit. However, this does only hold for the case of *two response categories*. If we have three categories and try to estimate in the same way by assigning the values 0,1,2 to the response categories, the trade-off ratios will be distorted.

8. How about Logit?

In the literature there is an alternative to the Probit model, viz. Logit analysis (see Cramer (2003) for a recent survey). Up to now there is no definite preference for one of the two modes. Some researchers like Logit better than Probit and vice versa. It is just a matter of tradition which method one chooses. Amemiya (1981) suggested that the Logit and Probit estimators differ only by a multiple of about 0.625 (see also Maddala p.22). He suggested that this was so, because the two distributions look very much alike. In this paper we argue that this is just a consequence of the general fact that both are representations of the same net of indifference curves.

A POLS- type approach to Logit is simple to construct. Assume that the representation is logistic, which implies a logistic distribution function. In that case we may define the logistic analogue of equation (3.1) by

$$p_i = L(\mu_i) - L(\mu_{i-1}) \quad (i = 1, ..., k)$$
(8.1)

Then we may define the conditional expectations $\overline{\mu}_{i_n, LOG}$ with respect to the logistic. For the formula we refer to Maddala (1983, p.369). We estimate the model

$$\dot{Z}_{i_n, LOG} = \sum_{0}^{m} \beta_{i,LOG} X_{in} + \dot{\varepsilon}_n$$
(8.2)

Now the variance of the standard Logit is $\frac{1}{3}\pi^2$. It follows that $\beta_{LOG} \approx \sqrt{\frac{1}{3}\pi^2} \cdot \beta_{POLS}$.

There is one problem which makes the logistic problematic. If the left-hand side of (8.2) is logistically distributed that must hold for the right-hand side as well. But the first term at the right hand tends to a normal variate due to the working of the Central Limit Theorem. This makes (8.2) logically inconsistent. It is for this reason that we do not recommend the Logit- specification.

9. Discussion and Conclusion.

In this paper we develop a linear –method that compares very well with the traditional Ordered Probit. The essential point is that we estimate the shape of indifference curves, that is, the trade-off ratios between coefficients. This method, which we call POLS, replaces the original dependent variable by its conditional mean. This new variable obeys the same trade-off relations as its underlying component. In the paper we show that the POLS yields almost the same outcomes as OP, except for a proportionality factor. If that situation does not hold, the POLS- procedure is attractive for the analysis of ordinal variables in its own right.

The essential difference between the traditional latent variable approach and our approach is that traditionally one starts to define the underlying model and its likelihood. We instead start by translating the observed ordered variable according to its conditional mean and applying OLS afterwards. In our approach we stay much closer to OLS and there is only a gradual difference between the treatment of continuously and discretely observable variables.

In presenting the new method, this paper contributes to the understanding of the Probit model. This is in itself interesting from a theoretical point of view. Nevertheless, the POLS method might not seem very relevant for present econometric and statistical practice, as the Probit- routine is included in most standard software packages. However, the POLS method is easily generalized to complex situations (such as panel data and system of equations), which are even nowadays not a matter of computational routine.

For example, consider the multi-Probit version of a SUR model where, say, *k* equation errors are correlated, this involves hard computations of *k*-dimensional integrals on a large scale. Here we may also use the POLS- trick by replacing all *k* variables to be explained by their POLS-analogues and estimating the corresponding SUR-equation system in a linear setting. We refer to Van Praag, Ferrer-i-Carbonell (2004) and to Van Praag, Frijters, Ferrer-i-Carbonell (2003) for empirical examples.

Another instance where the POLS-approach is very helpful is when we employ Probit type-variables in longitudinal analysis with inter-temporal correlations. While for ordered response variables the use of panel techniques becomes difficult (see Greene (2005), Ferrer-i-Carbonell and Frijters 2004)), such econometric techniques are very easy to implement if using the POLS method. We again refer to Van Praag and Ferrer-i-Carbonell (2004) for empirical examples.

The approach is also helpful when we want to employ ordered variables as explanatory variables. In this case, we can plug in the conditional mean as explanatory variable. Examples are found Van Praag and Baarsma (2005) and Van Praag and Ferrer–i-Carbonell (2004). It is a matter of course that the usual identification problems and their solutions hold. Identification does not become more difficult but not easier either. Next to the above-mentioned examples, the POLS can also be applied to factor analysis and principal components.

The most important result of our findings is that a good part of the methods of traditional discrete response analysis may be replaced by POLS and its generalizations, utilizing a POLS- transformation of the data. Not only are the OLS-variants computationally easier than the discrete methods that require the computation of many integrals and or Monte Carlo simulations, but also they open the way to the application of linear classical methods to discrete response data.

One thing we should always keep in mind: discrete observation instead of observation on a continuous scale necessarily implies a loss of information. This loss of information will have an impact on the standard deviations, which become larger, and on the correlations, which will become smaller in an absolute sense than under continuous observation. This is the price to be paid for discrete observation. However, this has nothing to do with a POLS - cardinalization. As we saw, the same loss in reliability has to be paid when applying a Probit –type method.

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